DICOM Correction Item

Correction Number: CP-1084				
Log Summary: Clarify Spatial Registration Description				
Type of Modification	Name of Standard			
Modify	PS 3.3 – 2009			
Rationale for Correction				
When reading the definition of the Spatial Registration Module and comparing the information to the examples in PS 3.17 Annex O it was not clear, how to interpret the definitions.				

Sections of documents affected

PS 3.3, Section C.20.2

Correction Wording: n.a.

Modify PS 3.3, C.20.2

C.20.2 Spatial Registration Module

Table C.20.2-1 defines the general Attributes of the Spatial Registration Module.

SPATIAL REGISTRATION MODULE ATTRIBUTES						
Attribute Name	Tag	Туре	Attribute Description			
Content Date	(0008,0023)	1	The date the content creation started.			
Content Time	(0008,0033)	1	The time the content creation started.			
Include Content Identification Macro	Table 10-12					
Registration Sequence	(0070,0308)	1	A sequence of one or more registration items. Each item defines a spatial registration <u>of the images referenced in</u> <u>that item to the Registered RCS</u> <u>established by this SOP instance to the</u> referenced images in that item . All referenced images are in the same spatial frame of reference or atlas.			
>Frame of Reference UID	(0020,0052)	1C	Identifies <u>the</u> a Frame of Reference <u>of the</u> <u>referenced data</u> , that may or may not be an image set (e.g. atlas or physical space). See C.7.4.1.1.1 for further explanation. Required if Referenced Image Sequence (0008,1140) is absent. May be present otherwise.			

Table C.20.2-1 PATIAL REGISTRATION MODULE ATTRIBUTES

		referenced data, registered in this sequence item. One or more items shall be present. Required if Frame of Reference UID (0020,0052) is absent. May be present otherwise.					
>>Include 'Image SOP Instance Reference Macro' Table 10-3							
(0070,0309)	1	A sequence that specifies one spatial registration. Exactly one item shall be present					
(3006,00C8)	3	User description or comments about the registration.					
(0070,030D)	2	Describes the information input into the registration process. Zero or one Items may be present in this Sequence.					
>>>Include 'Code Sequence Macro' Table 8.8-1							
(0070,030A)	1	One or more items shall be present. <u>Specifies one transformation, that</u> <u>registers the Source RCS/images to the</u> <u>Registered RCS. It is expressible as</u> <u>multiple matrices, each in a separate</u> <u>item of the sequence. Each item</u> <u>specifies a transformation.</u> The item order is significant and corresponds to matrix multiplication order. See C.20.2.1.1.					
(3006,00C6)	1	A 4x4 homogeneous transformation matrix that registers <u>a coordinate system A to B</u> the referenced images to the local RCS. Matrix elements shall be listed in row-major order. See C.20.2.1.1.					
(0070,030C)	1	Type of Frame of Reference Transformation Matrix (3006,00C6). Defined terms: RIGID RIGID_SCALE AFFINE See C 20 2 1 2					
	rence Macro' Tal (0070,0309) (3006,00C8) (0070,030D) able 8.8-1 (0070,030A) (3006,00C6) (0070,030C)	rence Macro' Table 10-3 (0070,0309) 1 (3006,00C8) 3 (0070,030D) 2 able 8.8-1 (0070,030A) (0070,030A) 1 (3006,00C6) 1 (3006,00C6) 1 (0070,030C) 1					

Modify PS 3.3, C.20.2.1.1

C.20.2.1 Registration Module Attribute Descriptions

C.20.2.1.1 Frame of Reference Transformation Matrix

The Frame of Reference Transformation Matrix (3006,00C6) ${}^{A}M_{B}$ describes how to transform a point (${}^{B}x$, ${}^{B}y$, ${}^{B}z$) with respect to RCS_B into (${}^{A}x$, ${}^{A}y$, ${}^{A}z$) with respect to RCS_A according to the equation below.

$$\begin{bmatrix} A \\ A \\ Y \\ A \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} M_{11} & M_{12} & M_{13} & T_x \\ M_{21} & M_{22} & M_{23} & T_y \\ M_{31} & M_{32} & M_{33} & T_z \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} B \\ B \\ y \\ B \\ z \\ 1 \end{bmatrix}$$

The Frame of Reference Transformation Matrix Registration is expressible as multiple matrices, each in a separate item of the Matrix Sequence (0070,030A). The equation below specifies the order of the matrix multiplication where M_1 , M_2 and M_3 are the first, second and third items in the sequence.

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